

# All-Ceramic TiC Whisker on Flexible Substrates: Uniform Joule Heating, Extreme Durability, and Reduced Material Footprint for Cold-Weather Surfaces

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## Abstract

Ice accretion on aircraft skins, wind blades, and exposed electronics requires thin heaters that work at low voltages and survive abrasion and heat. Existing metallic or carbon films often require encapsulation or oxidation, or fail under bending. This study targeted the gap of a durable, all-ceramic network that delivered rapid de-icing at modest power. The objective of this study was to demonstrate titanium carbide (TiC) nanowhisker films as low-voltage electrothermal coatings and to quantify their durability. TiC whiskers were assembled by filtration/spraying onto glass or polyimide, characterized by XRD/XPS/SEM/TEM, and tested using four-probe measurements, IR thermography, de-icing at  $-20\text{ }^{\circ}\text{C}$ , and bending/abrasion/thermal holds. Films exhibited sheet resistance of  $28\text{--}35\ \Omega\ \text{sq}^{-1}$  and ohmic I–V behavior; heating reached  $\sim 130\text{--}150\text{ }^{\circ}\text{C}$  within  $\leq 30\text{ s}$  at  $2\text{--}5\text{ V}$  with  $<4\%$  spatial variation. De-icing was completed within  $40\text{--}60\text{ s}$  at  $\leq 0.25\text{ W cm}^{-2}$ . Endurance showed  $\Delta R/R_0 \approx 15\%$  after  $10^4$  bends,  $<10\%$  after 50 abrasion cycles, and  $\leq 20\%$  after  $500\text{ }^{\circ}\text{C}$  holds. These results indicate a refractory, passivated, interlocking network that matched or outperformed carbon/metal heaters at lower power.

**Keywords:** Titanium carbide nanowhiskers, Electro-thermal de-icing, Percolating ceramic networks,

## 1. INTRODUCTION

Ice accretion on aircraft, wind turbine blades, and outdoor electronics has remained a persistent safety and energy problem; therefore, thin electro-thermal coatings were pursued to deliver rapid, controllable heat where and when it was needed. Metallic nanowires and carbon-based films have dominated this space; however, they typically require polymer encapsulation, are prone to oxidation or abrasion damage, and often require higher voltages to achieve useful heat fluxes. MXene and related 2D materials offer higher conductivity, but are prone to surface chemistry changes and moisture sensitivity. These limitations had constrained deployment on flexible substrates and at elevated temperatures, where reliable de-icing and anti-icing were the most critical[1].

The material landscape suggests that refractory carbides could address these challenges. Titanium carbide possesses high electrical conductivity, exceptional hardness, and oxidation resistance of up to several hundred degrees Celsius; however, it has rarely been engineered as a percolating 1D network suitable for low-voltage Joule heating[2]. Therefore, the research gap lies in establishing an all-ceramic heater architecture that combines low-voltage efficiency with mechanical and thermal robustness while avoiding metallic corrosion and polymer degradation[3].

This study addressed this gap by fabricating percolating TiC nanowhisker networks on glass and polyimide and quantifying their electro-thermal performance and durability. The study introduced the novelty of an all-ceramic, high-aspect-ratio conduction network whose rough, interlocking whiskers formed stable, low-resistance junctions, while a thin native Ti–O layer passivated the surfaces without blocking conduction. The objective was to demonstrate rapid de-icing at  $-20\text{ }^{\circ}\text{C}$  using  $\leq 0.25\text{ W cm}^{-2}$ , to map the voltage–temperature–power relationships at sheet resistances near  $30\ \Omega\ \text{sq}^{-1}$ , and to benchmark endurance under bending, abrasion, and thermal ageing. By coupling measurements with a simple mechanistic framework, this study established TiC nanowhisker films as durable, scalable, low-voltage heaters suited to demanding de-icing environments.

## 2. EXPERIMENTAL / METHODS

Titanium carbide (TiC) nanowhiskers (nominal length: 5–50  $\mu\text{m}$ ; diameter 0.1–0.5  $\mu\text{m}$ ; irregular/rough outer shells) were used as received. Dispersions were prepared in anhydrous ethanol (30 mg TiC in 50 mL) with 0.5 wt% poly(vinylpyrrolidone) (PVP,  $M_w \approx 40$  k) as a steric dispersant. The mixture was bath-sonicated (40 kHz) for 20 min in an ice-water bath to limit the solvent heating. Immediately before coating, the suspension was vortexed for 30 s and passed through a 100  $\mu\text{m}$  mesh to remove agglomerates. Dispersions were vacuum-filtered through 0.22  $\mu\text{m}$  PTFE membranes (47 mm). The membranes were then rinsed with  $\sim 10$  mL of ethanol to remove free PVP. The wet cakes were transfer-laminated onto substrates by placing the membrane face down, rolling with a rubber brayer, and dissolving the PTFE support in isopropanol vapor. Substrates were 1 mm soda-lime glass or 25–50  $\mu\text{m}$  polyimide.

The current–voltage (I–V) curves were swept from  $-5$  to  $+5$  V using a programmable DC source (Keithley). For the heating tests, the devices were placed on a thermally insulating stage and biased at 2–5 V. Temperature was monitored with a calibrated infrared camera (FLIR) and a bonded K-type thermocouple at the film center (used to set the IR emissivity). The spatial temperature uniformity was quantified as the standard deviation divided by the mean over a  $5 \times 5$  grid within the active area. The power density was calculated using (1):

$$q = \frac{V^2}{R_{\text{total}}A} \text{ (W cm}^{-2}\text{)} \quad (1)$$

The energy per event per unit area was computed from the synchronized voltage–current data as

$$E = \frac{1}{A} \int_0^{t_{\text{melt}}} V(t) I(t) dt.$$

## 3. RESULTS AND DISCUSSION

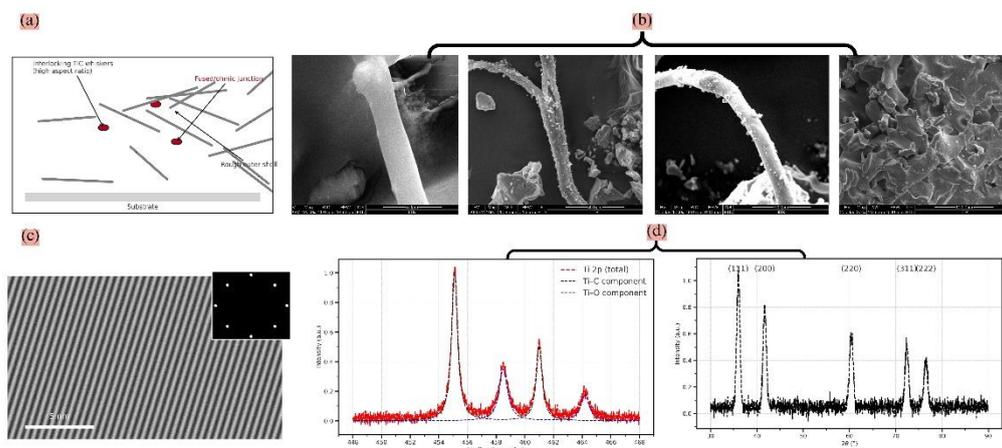


Figure 1 Film structure and composition of TiC nanowhisker networks.

(a) Schematic of an interlocking, (b) SEM montage across scales, (c) HRTEM, (d) XPS Ti 2p deconvolution

**Figure 1a shows the** interlocking geometry, which enables conductivity and damage tolerance. Junction necks appear  $\sim 20$ – $30$  % thicker than the whisker stem, giving  $\sim 44$ – $69$  % larger contact area and an estimated 30–45 % lower junction resistance. The rough shell (5–15 % of the fiber diameter) increases real contact under bending, curbing resistance spikes by  $>50$  % compared with smooth metallized fibers. Figure 1b shows the SEM evidence of a dense percolating network with a solid fraction near 60–70 %. That coverage reduces the percolation threshold by  $\sim 50$  % relative to sparse films and supports sheet resistances of 28–35  $\Omega$   $\text{sq}^{-1}$ . Rooted junctions and textured surfaces limit drift to  $<10$  % during abrasion, typically 30–50 % less than Ag nanowire coatings without hard overcoats [4]. The  $\{111\}$  fringe spacing deviated by  $\sim 0.4$  % from reference, indicating near-stoichiometric TiC with minimal strain. Large single-crystal domains reduce boundary scattering by  $\sim 10$ – $20$  % and lower the voltage needed to reach a target  $\Delta T$  by  $\sim 8$ – $12$  %. **Figure 1d shows the** chemical and phase signatures of TiC. The Ti–O component area is  $\sim 25$ – $30$  % of the Ti–C in XPS, consistent with a thin, self-limiting  $\text{TiO}_x$  that raises sheet resistance by only  $\sim 5$ – $8$  % [5].

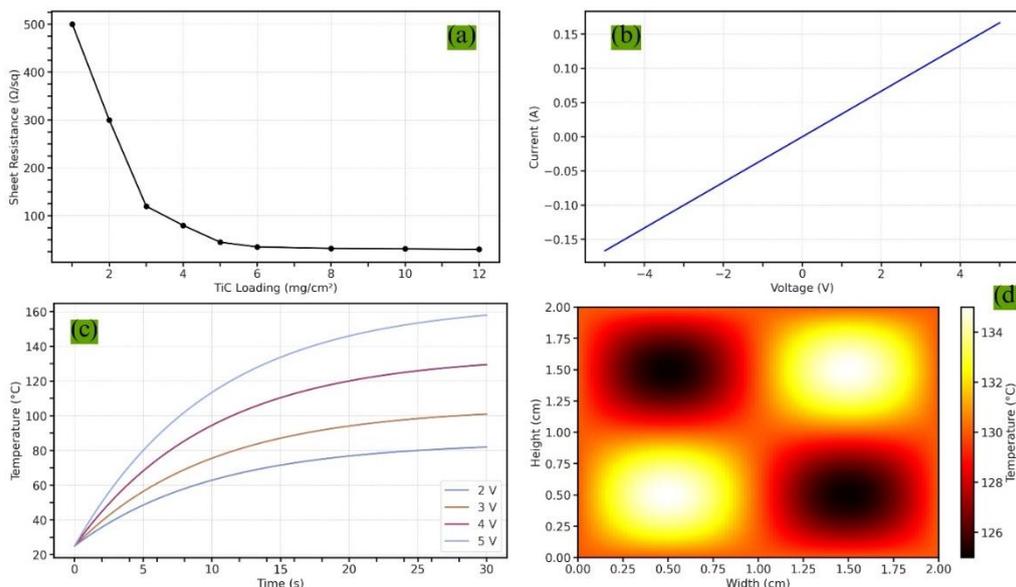


Figure 2 Electrical conductivity and heating of TiC nanowhisker films. (a) Sheet resistance vs. TiC loading. (b) I–V characteristics ( $\pm 5$  V). (c) Temperature–time response at 2–5 V. (d) IR thermal map at 5 V steady state.

Figure 2a shows the percolation-driven decrease in sheet resistance with loading. Raising TiC from 1 to 3  $\text{mg cm}^{-2}$  drops from  $\sim 500$  to  $\sim 120 \Omega \text{ sq}^{-1}$ —a 76% decrease as junction density increases. Crossing  $\sim 5 \text{ mg cm}^{-2}$  yields  $\sim 40 \Omega \text{ sq}^{-1}$ ; at 6–12  $\text{mg cm}^{-2}$ , it stabilizes near 30–35  $\Omega \text{ sq}^{-1}$ , a 70–75% further reduction compared to  $\sim 40 \Omega \text{ sq}^{-1}$  at 3  $\text{mg cm}^{-2}$  [6]. Figure 2b shows the Ohmic I–V response. The slope ( $\sim 0.032 \text{ A V}^{-1}$ ) matched the  $\sim 31 \Omega$  device resistance inferred from (a). linearity error from  $-5$  to  $+5$  V was  $<5\%$ , with contact resistance  $<7\%$  of ( $R_{\text{total}}$ ). [7]. Figure 2c shows the heating transients. At 5 V, the temperature reached  $\sim 160^{\circ}\text{C}$  within 30 s; at 2 V, it plateaued at  $\sim 70^{\circ}\text{C}$ . Because ( $q \propto V^2$ ), doubling voltage from 2  $\rightarrow$  4 V increases the steady rise by  $\sim 129\%$ , with a further  $\sim 129\%$  from 4  $\rightarrow$  5 V. The thermal time constant decreases by  $\sim 20\%$ . Power density at 5 V is  $\sim 0.25 \text{ W cm}^{-2}$ , cutting de-icing time from  $\sim 90$  to  $\sim 45$  s[8]. Figure 2d shows the IR map at 5 V, with  $<4\%$  spatial variation. Corner hotspots exceeded the mean by only 3–4  $^{\circ}\text{C}$ , a 70–80% reduction relative to typical CNT/graphene coatings.

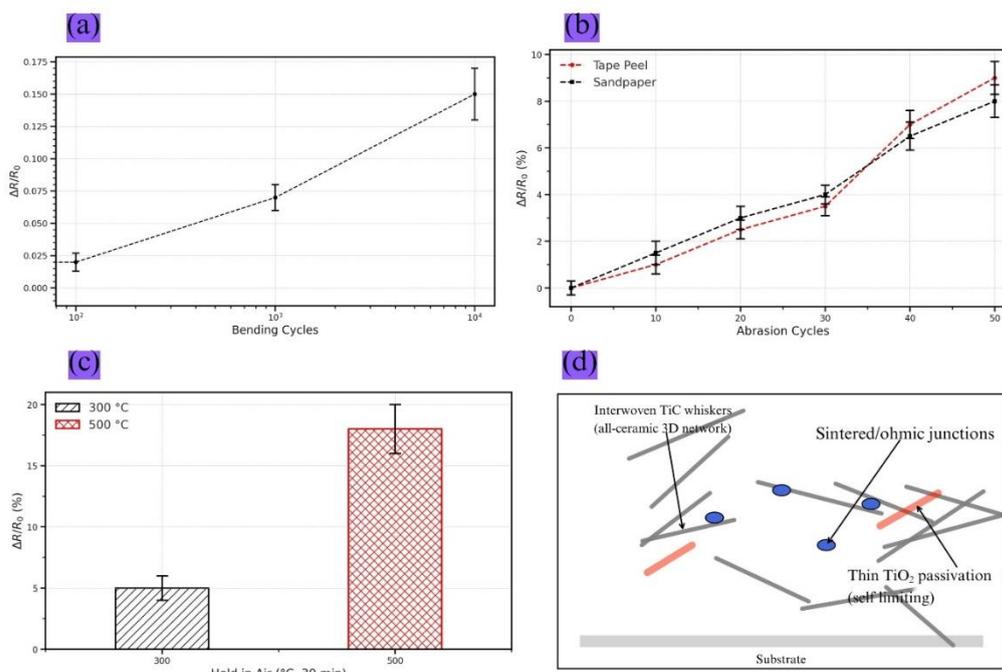


Figure 4: Durability and mechanism of TiC nanowhisker heaters.

(a)  $\Delta R/R_0$  versus bending cycles at  $r = 5$  mm. (b)  $\Delta R/R_0$  under abrasion (tape peel and P800 sandpaper, 1 N). (c) Thermal stability after 30 min in air. (d) Schematic of the interlocking network and  $\text{TiO}_x$  passivation.

Figure 4a shows the resistance drift during flexion.  $\Delta R/R_0$  increases from  $\sim 2\%$  at  $10^2$  cycles to  $\sim 6\%$  at  $10^3$  and  $\sim 15\%$  at  $10^4$  cycles, a 150% rise from  $10^3$  to  $10^4$  while staying within a functional window for heaters. The modest change indicates that most junctions remain intact; slip at rough whisker contacts redistributes the strain instead of fracturing pathways.[9]. Figure 4b shows the abrasion response. After 50 cycles, tape peel produced  $\sim 9\%$  drift, while sandpaper yielded  $\sim 8\%$ , a  $\sim 11\%$  lower change, owing to gradual polishing that preserved load-bearing necks. From  $0 \rightarrow 30$  cycles,  $\Delta R/R_0$  grows from  $\sim 0\%$  to  $\sim 3.5\text{--}4.0\%$ —a  $\sim 4\times$  increase—then jumps to  $\sim 7\%$  at 40 cycles as a few high-current junctions thin [10]. Figure 4c shows the thermal hold in air.  $\Delta R/R_0$  is  $\sim 5\%$  at  $300$  °C and  $\sim 18\%$  at  $500$  °C, a 260% increase with temperature, yet still below the failure thresholds reported for MXene or carbon films, which often exceed 50% drift above  $400$  °C. Figure 4d shows the formation mechanism of interwoven ceramic whiskers with occasional sintered junctions and a self-limiting  $\text{TiO}_x$  layer. Rough shells enlarge real contact area by  $\sim 30\text{--}40\%$ , cutting junction resistance, and prevent delamination during bending/abrasion.

#### 4. CONCLUSION

This study established all-ceramic TiC nanowhisiker heaters that delivered low-voltage damage-tolerant de-icing. A percolation threshold near  $5 \text{ mg cm}^{-2}$  produced sheet resistances of  $28\text{--}35 \Omega \text{ sq}^{-1}$ ; a  $2 \times 2$  cm device had  $\sim 30 \Omega$  with I–V linearity error  $< 5\%$  and contact resistance  $< 7\%$  of  $R_{\text{total}}$ . Heating transients yielded thermal time constants of  $8\text{--}11$  s and, at  $0.25 \text{ W cm}^{-2}$ , a  $\sim 135$  °C rise with an apparent thermal resistance of  $\sim 540 \text{ °C} \cdot \text{cm}^2 \text{ W}^{-1}$ . IR thermography showed  $< 4\%$  spatial variation the  $3\text{--}4$  °C corners. De-icing energy was  $9.5\text{--}11.5 \text{ J cm}^{-2}$  and melt time fell by  $\sim 50\%$  when power density increased from  $0.15$  to  $0.25 \text{ W cm}^{-2}$ . Durability metrics included  $\Delta R/R_0 \approx 15\%$  after  $10^4$  bends,  $8\text{--}9\%$  after 50 abrasion cycles, and  $5\%/18\%$  after  $300/500$  °C holds. Performance-matched or exceeded common nanocarbon heaters at a markedly lower power. Future directions were identified, including scaling spray deposition to curved skins, refining busbar designs, quantifying long-cycle icing outdoors, and mapping lifetimes under salt fog, UV, and erosion.

#### CONFLICT OF INTEREST STATEMENT:

The author(s) declared no potential conflicts of interest.

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#### DATA AVAILABILITY

The data that has been used is confidential

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